

# JUSTIN LIANG

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## EDUCATION

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### University of Toronto

Sept 2016 - May 2018

Master of Science, Computer Science

*Machine Learning Group*

Supervisor: Raquel Urtasun

GPA: 4.00, A+

### University of British Columbia

Sept 2011 - May 2016

Bachelor of Applied Science, Mechanical Engineering

*Mechatronics Option*

90.3/100 — Rank: 1/34, A+

## PUBLICATIONS

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S.Duggal, Z. Wang, W.C. Ma, S. Manivasagam, **J. Liang\***, S. Wang, R. Urtasun. Mending Neural Implicit Modeling for 3D Vehicle Reconstruction in the Wild. (WACV 2022)

N.Homayounfar, **J. Liang\***, W.C. Ma, R. Urtasun. VideoClick: Video Object Segmentation with a Single Click. (Arxiv 2021)

N.Homayounfar\*, Y. Xiong\*, **J. Liang\***, W.C. Ma, R. Urtasun. LevelSet R-CNN: A Deep Variational Method for Instance Segmentation. (ECCV 2020)

**J. Liang**, N.Homayounfar, W.C. Ma, Y. Xiong, R. Hui, R. Urtasun. PolyTransform: Deep Polygon Transforming for Instance Segmentation. (CVPR 2020)

N.Homayounfar, W.C. Ma, **J. Liang**, X. Yu, J. Fan, R. Urtasun. Learning to Map by Discovering the Deep DAG Topology (ICCV 2019)

**J. Liang\***, N. Homayounfar\*, W. C. Ma, S. Wang, R. Urtasun. Convolutional Recurrent Network for Road Boundary Extraction. (CVPR 2019)

**J. Liang**, R. Urtasun. End-to-End Deep Structured Models for Drawing Crosswalks. (ECCV 2018)

S. Wang, M. Bai, G. Mattyus, H. Chu, W. Luo, B. Yang, **J. Liang**, J. Cheverie, S. Fidler, R. Urtasun. TorontoCity: Seeing the World with a Million Eyes. (ICCV 2017, **Spotlight**)

## RESEARCH EXPERIENCE

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### Research Assistant, Machine Learning Group, Dept. of Computer Science, UofT

Sept 2016 - May 2018

#### Advisor: Prof. Raquel Urtasun

- Designed models using neural networks to automatically map the world.
- Performed building footprint shape reconstruction on aerial images.
- Developed algorithms to automatically annotate crosswalks.
- Implemented a model to automatically classify lane markings.

### Research Assistant, Clean Energy Research Lab, Dept. of Mechanical Engineering, UBC

May 2013 - Aug 2013

#### Advisor: Prof. Steven Rogak, Dr. James Montgomery

- Designed experimental setup to test HVAC filters.

- Conducted analysis to predict energy use and operation cost of HVAC filters.

## WORK EXPERIENCE

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|---|-----------------------|
| <b>Research Scientist II, Waabi</b>   | Mar 2021 - Present    |
| · Working on machine learning algorithms for autonomous vehicles                    |                       |
| <b>Research Scientist II, Uber ATG</b>  | Sept 2018 - Feb 2021  |
| · Worked on machine learning algorithms for autonomous vehicles                     |                       |
| <b>Research Scientist I, Uber ATG</b>   | Oct 2017 - Aug 2018   |
| · Worked on machine learning algorithms for autonomous vehicles                     |                       |
| <b>Research Intern, Uber ATG</b>  | July 2017 - Sept 2017 |
| · Worked on machine learning algorithms for autonomous vehicles                     |                       |
| <b>Software Development Intern, Verity Studios (ETH Spin-Off)</b>                   | Jan 2015 - Aug 2015   |
| · Built a parameter server in C++ to save and load parameter data onto quadcopters. |                       |
| · Developed user interfaces using Qt and ROS.                                       |                       |
| <b>Controls Systems Engineer, Brock Solutions</b>                                   | May 2014 - Aug 2014   |
| · Wrote VBA scripts to automatically generate excel checklists.                     |                       |
| · Troubleshooted PLC ladder logic for controlling luggage conveyors at YVR.         |                       |
| <b>Controls Design Support Engineer, Confirmed Automation Systems</b>               | Sept 2013 - Dec 2013  |
| · Designed mechanical and hardware solutions for industrial processing plants.      |                       |

## VOLUNTEER EXPERIENCE

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| <b>Software Engineer, UBC Snowbots School Team</b>        | Sept 2014 - Aug 2015 |
| · Implemented pathfinding algorithms on autonomous robot. |                      |
| <b>Electrical Engineer, UBC SuperMileage School Team</b>  | Sept 2012 - Apr 2013 |
| · Built test setup to evaluate vehicle performance.       |                      |

## AWARDS AND HONOURS

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| Google Travel and Conference Grant (CVPR 2017)                      | 2017       |
| University of Toronto Graduate Fellowship                           | 2016       |
| Letson Prize  | 2016       |
| Frank Vernon Memorial Scholarship 2x                                | 2015, 2013 |
| Charles and Jane Banks Scholarship                                  | 2014       |
| NSERC Undergraduate Student Research Award                          | 2013       |
| Trek Excellence Scholarship 2x                                      | 2013, 2012 |
| Association of Professional Engineers and Geoscientists Scholarship | 2012       |
| British Columbia Government Scholarship                             | 2012       |
| Top Science Student Award (Secondary School)                        | 2011       |
| Euclid Math Contest School Champion (Secondary School)              | 2011       |

## PATENTS

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N.Homayounfar, Y Xiong, **J. Liang**, W.C.Ma, R.Urtasun. High Quality Instance Segmentation. U.S. Patent Application 17/017,104 (2021)

**J. Liang**, N. Homayounfar, W.C. Ma, Y. Xiong, R. Urtasun. Systems and Methods for Predicting Instance Geometry. U.S. Patent Application 17/007,667 (2021)

N. Homayounfar, **J. Liang**, R. Urtasun. System and Methods for Generating High Definition Maps Using Machine-Learned Models to Analyze Topology Data Gathered From Sensors. U.S. Patent Application 16/825,518 (2020)

**J. Liang**, R. Urtasun. Structured Prediction Crosswalk Generation. U.S. Patent Application 16/183,012. (2019)

**J. Liang**, R. Urtasun. Map Automation-Lane Classification. U.S. Patent Application 16/353,871 (2019)

## SKILLS

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**Languages** Python, C, C++, MATLAB

**Scientific Packages** Pytorch, NumPy, Shapely, OpenCV